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Roll No. :

328455(28)

B. E. (Fourth Semester) Examination, 2020
APR-MAY 2022
(New Scheme)

(ET & T Engg. Branch)

SIGNALS and SYSTEMS

Time Allowed : Three hours

Maximum Marks : 80

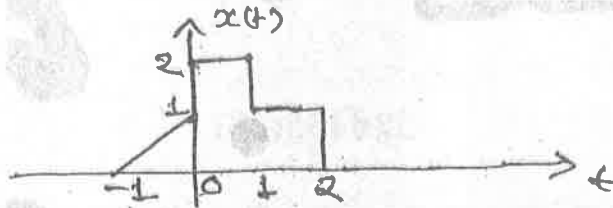
Minimum Pass Marks : 28

Note : Part (a) of each question is compulsory & carries 2 marks. Solve any two from (b), (c) and (d) and carries 7 marks.

Unit-I

1. (a) Define invertible system,
- (b) For the signal $x(t)$ shown in figure, sketch the following signals :

[2]



(i) $x(t-2)$

(ii) $x(2t+3)$

(iii) $x(-t+1)$

(c) Given a trapezoidal pulse :

$$x(t) = \begin{cases} t+5, & -5 \leq t \leq -4 \\ 1, & -4 \leq t \leq 4 \\ 5-t, & 4 \leq t \leq 5 \end{cases}$$

Determine the total energy and power of $x(t)$. Also find the total energy and power of the differentiated signal :

$$y(t) = \frac{d}{dt} x(t)$$

(d) Check whether the following system are :

(i) Static or dynamic

(ii) Linear or non-linear

(iii) Causal or non causal

[3]

(iv) Time invariant or time variant

$$y(n) = \sum_{k=0}^{n+1} x(k+1)$$

Unit-II

2. (a) Define Hilbert transform.

(b) State and prove following properties of a continuous time fourier transform.

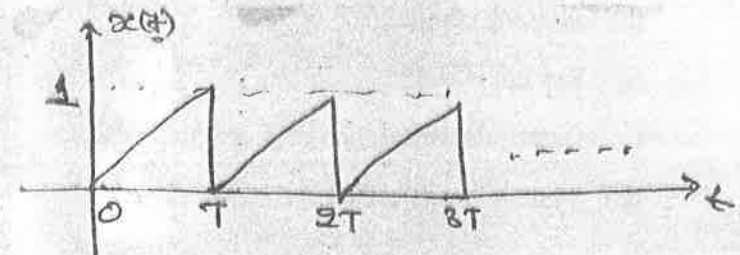
(i) Scaling

(ii) Time shifting

(iii) Linearity

(c) Find the fourier transform and energy spectral density of $x(t) = Ae^{at}u(-t)$. Also plot the amplitude and phase spectra.

(d) Determine the exponential fourier series for the periodic sawtooth waveform as shown in fig. :



Unit-III

3. (a) Write the condition for stability and causality of any discrete sequence $h(n)$.
- (b) State and prove following properties of Z-transform :
- Time shifting.
 - Differentiation
- (c) Find $X(z)$ and sketch the ROC of $x(n) = a^n$ for $a < 1$ and $a > 1$.
- (d) A linear time invariant is characterized by the system function :

$$H(z) = \frac{1}{1 - 2.5z^{-1} + z^{-2}}$$

Specify the ROC of $H(z)$ and determine $h(n)$ for the following conditions :

- System is stable
- System is causal
- System is anti-causal

Unit-IV

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4. (a) Define transfer function.
- (b) Explain the following properties of continuous time LTI system in term of impulse response :
- Memory less LTI system
 - Causal LTI system
 - Stable LTI system
- (c) Obtain the graphical convolution of $x(t) = u(t) - u(t-3)$ and $h(t) = u(t) - u(t-2)$.
- (d) Consider on LTI system with differential equation
- $$\frac{d^2 y(t)}{dt^2} + 4 \frac{dy(t)}{dt} + 3y(t) = \frac{dx(t)}{dt} + 2x(t)$$
- find the frequency response and impulse response.

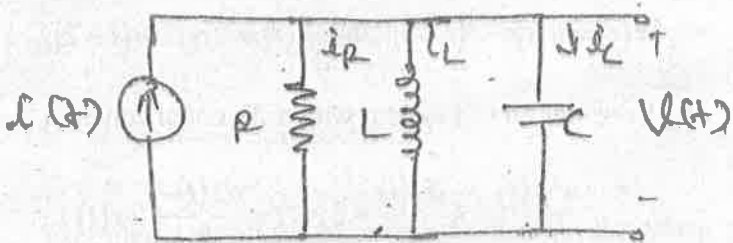
Unit-V

5. (a) What are the advantages of representing system in state space representation?
- (b) Find the state space representation of the following system whose differential equation representation is :

[6]

$$\begin{aligned} \frac{d^3 y(t)}{dt^3} + 3 \frac{d^2 y(t)}{dt^2} + 5 \frac{dy(t)}{dt} + 6y(t) \\ = \frac{d^2 x(t)}{dt^2} + \frac{6 dx(t)}{dt} + 5x(t) \end{aligned}$$

(c) Obtain the state model of the parallel RLC network as shown in below fig.



(d) Find state equation of a discrete time system described by

$$y(n) - \frac{3}{4}y(n-1) + \frac{1}{8}y(n-2) = x(n)$$